

An Introduction to Knot Theory from String Theory



In this talk I'll basically summarise some of the recent works on topological field theory and knots that I have started. The talk will be based on the following papers. In this talk I'll basically summarise some of the recent works on topological field theory and knots that I have started. The talk will be based on the following papers.

- Knot Invariants and M-Theory I: Hitchin Equations, Chern-Simons Theory and Surface Operators, K.D, Veronica Errasti Diez, P. Ramadevi and Radu Tatar 1608.05128.
- A Companion to Knot Invariants and M-Theory I: Proofs and Derivations, Veronica Errasti Diez, 1702.07366
- Fivebranes and Knots, Edward Witten, 1101.3216
- Electric Magnetic Duality and the Geometric Langland Programme, Anton Kapustin and Edward Witten, hep-th/0604151
- Knot Invariants and M-Theory II, K.D, Veronica Errasti Diez, K. Gopala Krishna, Rohit Jain, P. Ramadevi and Radu Tatar To appear

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Dasgupta (McGill)

vancouver. Iviay 51, 2019, 2.50 pm

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Veronica Errasti Diez

Dasgupta (McGill)

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Veronica Errasti Diez

P. Ramadevi



String Theory

vancouver. Iviay 51, 2019, 2.30 pm





Radu Tatar

Veronica Errasti Diez

P. Ramadevi

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Outline of the talk

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• A very brief introduction to knot theory and Chern-Simons theory

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- Getting the full topological action from M-theory
- Towards knot theory from M-theory
- Discussions and conclusions

What are the mathematical knots?

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What are the mathematical knots?

Inspired by daily life in shoelaces and rope, a mathematical knot differs in that the ends are joined so that it cannot be undone.





Other examples can be tabulated in the following way



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String Theory





Two knots are defined to be equivalent if there is an ambient isotopy between them



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String Theory

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String Theory

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Who famously developed the three Reidemeister moves

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Solution:



Thus using untwist, poke and slide moves, allows us to see the above simplification!

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Jones provided a criteria to compute polynomial invariants for knots that continues to be used today to distinguish knots. These polynomials are called the Jones polynomials.

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String Theory

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What Witten concluded was something interesting.

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$$J(\mathbf{K}, \mathbf{R}, \mathbf{q}) = \langle W(\mathbf{K}, \mathbf{R}) \rangle$$

$$= \int \mathcal{D}A \exp\left[ik \int_{\mathbf{R}^3} \operatorname{Tr}\left(A \wedge dA + \frac{2}{3}A \wedge A \wedge A\right)\right] \operatorname{Tr}_{B}P \exp\left(\oint_{\mathbf{K}}A\right)$$

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Furthermore, what Witten concluded was even more fascinating.

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$$J(\mathbf{K},q)=\sum_n a_n q^n$$

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where a_n could be integers and q, which can now be identified with \sqrt{t} from Jones, is given by the Chern-Simons coupling constant k and some dual Coxeter number h of G as

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$$q = \exp\left(\frac{2\pi i}{k+h}\right)$$

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Similarly for the fundamental representation of SO(N), we get the Kauffman polynomials.

Besides the well known polynomials, we can obtain many new generalised knot invariants

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Besides the well known polynomials, we can obtain many new generalised knot invariants, all by using the Chern-Simons theory!

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Khovanov's observation is easy to state (at least).

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This means the a_n coefficients of the Jones polynomial can be viewed as dimensions of certain vector spaces.

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All this is great, and hopefully explains many things.





Is there an easier way to understand and appreciate some of the above-mentioned mathematical ideas?



Is there an easier way to understand and appreciate some of the above-mentioned mathematical ideas? This is where string theory comes to our rescue!







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Despite the size, it is an immensely readable paper and discusses many interesting facets of S-duality related to the Euclideanized version of $\mathcal{N} = 4$ supersymmetric YM theory.

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What has BHN equation anything to do with knot theory?

Dasgupta (McGill)

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What has BHN equation anything to do with knot theory? This is exactly the question that Witten asked in 2011 and he found an interesting answer.

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$$J(\mathbf{K},q)=\sum_n a_n q^n$$





Many questions now arise

Dasgupta (McGill)

String Theory

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Many questions now arise: What set-up are we talking about?

Dasgupta (McGill)

String Theory

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Many questions now arise: What set-up are we talking about? How do we distinguish the knots using instanton numbers? Where is the topological field theory? Why on earth would solutions of certain differential equations have anything to do with knot polynomials? At least we now have some understanding to answer all the questions that I raised here.

At least we now have some understanding to answer all the questions that I raised here. However the margin (of time) is too small to answer them here! So I'll only answer two questions At least we now have some understanding to answer all the questions that I raised here. However the margin (of time) is too small to answer them here! So I'll only answer two questions: What set-up are we talking about? At least we now have some understanding to answer all the questions that I raised here. However the margin (of time) is too small to answer them here! So I'll only answer two questions: What set-up are we talking about? and At least we now have some understanding to answer all the questions that I raised here. However the margin (of time) is too small to answer them here! So I'll only answer two questions: What set-up are we talking about? and Where is the topological field theory? At least we now have some understanding to answer all the questions that I raised here. However the margin (of time) is too small to answer them here! So I'll only answer two questions: What set-up are we talking about? and Where is the topological field theory?

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This doesn't entail the full Khovanov homology, but is a step towards that direction.

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The dotted lines being the NS5-brane and the solid lines are the D3-branes. The intersection is three-dimensional i.e along (x_0, x_1, x_2) directions in Euclidean space.

Dasgupta (McGill)

String Theory

Although the brane set-up is simple, the topological theory that appears at the intersection boundary is much more non-trivial to derive.

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The procedure to derive the full three-dimensional boundary action, which is both topological and supersymmetric, is a long and tedious procedure, but the final result is relatively straightforward. This is given by a Chern-Simons theory

$$S_b = \operatorname{Tr}\left(A \wedge dA + \frac{2i}{3}A \wedge A \wedge A\right)$$

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You might ask what's the big deal here? While without doing any computations one might have predicted the boundary 3d theory to be of the Chern-Simons kind, but the subtlety is that the gauge field that appears in S_b is not the Chern-Simons gauge field A!

$$A = \mathcal{A} + t\phi$$

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where *t* is a parameter that distinguishes various topological field theories, i.e for every choice of *t* there exists a topological field theory.

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Note that under twisting, the $\mathcal{N} = 4$ scalar fields action gets a contribution from the intersection region in such a way so as to tag along with the gauge field \mathcal{A} to give us precisely a Chern-Simons action S_b ! And that's the miracle!

The contribution from the intersection region of the NS5-D3 system that Witten found is rather subtle

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The answer turns out to be yes, by dualizing the Witten's set-up to M-theory.

The contribution from the intersection region of the NS5-D3 system that Witten found is rather subtle and, although this entails most of the key discussions of topological field theory in this set-up, is rather hard to visualize. Is there a simpler way to see this contribution and derive the boundary theory?

The answer turns out to be yes, by dualizing the Witten's set-up to M-theory. Once we insert another parallel NS5-brane at the other end of the D3-branes and dualize this to M-theory, the branes disappear and are converted to geometry in M-theory!

The θ angle dualize to G-fluxes in M-theory, so together we have only geometry and fluxes in M-theory.

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The θ angle dualize to G-fluxes in M-theory, so together we have only geometry and fluxes in M-theory. The precise M-theory configuration turns out to be a non-compact seven-manifold that is a *N*-centered warped Taub-NUT space *TN_N*, fibered over a compact three-dimensional base Σ_3 . The θ angle dualize to G-fluxes in M-theory, so together we have only geometry and fluxes in M-theory. The precise M-theory configuration turns out to be a non-compact seven-manifold that is a *N*-centered warped Taub-NUT space *TN_N*, fibered over a compact three-dimensional base Σ_3 .

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The geometry in M-theory is parametrized by certain warp factors $(F_1(r), \tilde{F}_2(r), F_3(r), F_4(r, ..))$ and the θ -term by θ .

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The geometry in M-theory is parametrized by certain warp factors $(F_1(r), \tilde{F}_2(r), F_3(r), F_4(r, ..))$ and the θ -term by θ . Most of the warp-factors are functions of the radial coordinate r, while F_4 is more generic.

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One might now worry that, since M_7 is non-compact, one cannot simply "compactify" M-theory on M_7 .

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How do we get the full non-abelian theory? The non-abelian enhancement occur exactly by the M2-brane states wrapped on the vanishing two-cycles of TN_N !

It turns out that one may effectively compactify the eleven-dimensional supergravity action over these harmonic forms to get an abelian gauge theory in four-dimensions!

How do we get the full non-abelian theory? The non-abelian enhancement occur exactly by the M2-brane states wrapped on the vanishing two-cycles of TN_N !

The story is very detailed, but thankfully straightforward.

After the dust settles, the four-dimensional Hamiltonian is easy to write down. This is given by

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which, as described in [11], can be made by picking the three scalar fields in \vec{X} and one scalar field from \vec{Y} (which we take here as φ_3). This means the complex σ field of [11], for our case will become:

$$\sigma \equiv A_r + iA_{\phi_1}. \quad (3.157)$$

The Gauss law constraint and the identification of the scalar fields will lead us to compute the Hamiltonian from the total effective action (3.153). Isolating the same scalar A_3 , the expression for the Hamiltonian, for the case when $c_2 = 0$ in (3.153), can be expressed as sum of squares of various terms in the following way:

$$\begin{aligned} &\mathcal{H} = \int d^{3}x \operatorname{Tr} \left\{ \sum_{i=1}^{2} \frac{c_{1}}{c_{2}} (\sqrt{c_{11}}\mathcal{F}_{a0} - \sqrt{c_{a1}}D_{a}A_{3})^{2} + \frac{c_{1}}{c_{3}} (\sqrt{c_{11}}\mathcal{F}_{a0} - \sqrt{c_{a1}}D_{a}A_{3})^{2} \right. \\ &+ \frac{c_{1}}{c_{3}} (\sqrt{c_{11}}\mathcal{F}_{b0} - \sqrt{c_{11}}D_{a}A_{3}A_{1})^{2} + \frac{c_{1}}{c_{3}} (\sqrt{c_{11}}\mathcal{F}_{a0} - \sqrt{c_{a1}}D_{a}A_{3})^{2} \\ &+ \frac{c_{1}}{c_{3}} (\sqrt{c_{11}}\mathcal{F}_{b0} - i\sqrt{c_{31}}D_{a}A_{3}A_{3})^{2} + \frac{c_{1}}{c_{3}} (\sqrt{c_{11}}\mathcal{F}_{a0}A_{a} - i\sqrt{c_{31}}D_{a}A_{a}A_{3})^{2} \\ &+ \frac{c_{1}}{c_{3}} (\sqrt{b_{10}}\mathcal{D}_{0}\varphi_{1} - i\sqrt{c_{31}}D_{a}A_{a}A_{3})^{2} + \frac{c_{1}(c_{30}}{c_{30}} (\mathcal{D}_{0}A_{3})^{2} + \frac{c_{1}^{2}}{c_{2}} (\sqrt{\frac{c_{1}c_{1}}{c_{2}}}\mathcal{F}_{a0}) \\ &+ \sqrt{\frac{c_{1}c_{2}}{c_{30}}} s_{a}^{(1)} c_{a0}\varphi_{0} \mathcal{D}_{a}A_{a} + \frac{\lambda}{a} + \sum_{a=1}^{3} \sum_{a=1}^{3} \sqrt{b_{4k}c_{a0}} \cdot m_{4k}^{(1)} \mathcal{D}_{b}\varphi_{k} \\ &- \sum_{k,l} ig_{abkl}^{(1)} \sqrt{d_{4l}} (\varphi_{a},\varphi_{l}) - \sum_{k=1}^{3} i \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(1)}} \mathcal{D}_{b}\varphi_{k} \\ &- \sum_{k,l} ig_{abkl}^{(1)} \sqrt{d_{4l}} (\varphi_{a},\varphi_{l}) - \sum_{k=1}^{3} i \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(1)}(\varphi_{a}, \varphi_{a}) \right) \\ &- ia_{a}^{(0)} \sqrt{\frac{c_{1}c_{1}}{c_{1}}} (\mathcal{A}_{a}, \mathcal{A}_{a}) \right)^{2} + \frac{(Q_{2k} + Q_{3k}) \delta^{3}x}{d_{11}} \\ &+ \sum_{k=1}^{3} \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) \right) \\ &+ \sqrt{\frac{c_{1}c_{2}c_{3}}{c_{1}c_{3}}} \left(g_{a}^{(2)}(\varphi_{a}, \varphi_{a}) + g_{a}^{(2)}(\varphi_{a}, \varphi_{a}) + g_{a}^{(2)}(\varphi_{a}, \varphi_{a}) \right) \\ &- ia_{a}^{(0)} \sqrt{\frac{c_{1}c_{1}}{c_{1}}} (\mathcal{A}_{a}, \mathcal{A}_{a}) \right)^{2} \\ &+ \sqrt{\frac{c_{1}c_{2}c_{3}}} \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \varphi_{a}) + g_{a}^{(2)}(\varphi_{a}, \varphi_{a}) \right) \\ &- ia_{a}^{(0)} \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) \right)^{2} \\ &+ \sqrt{\frac{c_{1}c_{2}c_{3}}} \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) \right)^{2} \\ &+ \sqrt{\frac{c_{1}c_{3}c_{3}}} \left(g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a}) + g_{a}^{(2)}(\varphi_{a}, \nabla_{b}A_{a})$$

where Q_E and Q_M are the electric and the magnetic charges respectively, which will be determined later; dim G is the dimension of the group; and $\delta \equiv (\alpha, \psi)$, $(y_2, y_3) \equiv (r, \phi_1)$. Most of coefficients appearing in (3.158) have been determined $\langle \overrightarrow{e_1} \rangle$

String Theory

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 $\mathcal{H} = \text{Sum of squares} + \mathbf{Q}_{\mathbf{E}} + \mathbf{Q}_{\mathbf{M}}$

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$$\begin{split} \mathcal{D}_{0}\mathcal{A}_{3} &= 0, \quad \left(\sqrt{b_{0k}} - \sqrt{c_{3k}}\right)^{2} \left[\mathcal{A}_{3}, \varphi_{k}\right]^{2} = 0\\ \left(\sqrt{c_{11}} - \sqrt{c_{\alpha3}}\right)^{2} \left(\mathcal{D}_{\alpha}\mathcal{A}_{3}\right)^{2} = 0, \quad \left(\sqrt{c_{12}} - \sqrt{c_{\psi3}}\right)^{2} \left(\mathcal{D}_{\psi}\mathcal{A}_{3}\right)^{2} = 0\\ \left(\sqrt{c_{0r}} - \sqrt{a_{2}}\right)^{2} \left[\mathcal{A}_{3}, \mathcal{A}_{r}\right]^{2} = 0, \quad \left(\sqrt{c_{0\phi_{1}}} - \sqrt{a_{4}}\right)^{2} \left[\mathcal{A}_{3}, \mathcal{A}_{\phi_{1}}\right]^{2} = 0. \end{split}$$

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$$c_{11}(\theta) = R_3 \sec \theta \int_0^\infty dr \ e^{2\phi_0} \sqrt{\frac{F_1 \widetilde{F}_2 F_3}{\widetilde{F}_2 - F_3}} \ln \left| \frac{\sqrt{\widetilde{F}_2 + \sqrt{\widetilde{F}_2 - F_3}}}{\sqrt{\widetilde{F}_2 - \sqrt{\widetilde{F}_2 - F_3}}} \right|$$
$$c_{\alpha 3}(\theta) = R_3 \sec \theta \int_0^\infty dr \ \frac{e^{2\phi_0}}{H_2} \sqrt{\frac{F_1 \widetilde{F}_2 F_3}{\widetilde{F}_2 - F_3}} \ln \left| \frac{\sqrt{\widetilde{F}_2} + \sqrt{\widetilde{F}_2 - F_3}}{\sqrt{\widetilde{F}_2 - \sqrt{\widetilde{F}_2 - F_3}}} \right|$$

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$$c_{11}(\theta) = R_3 \sec \theta \int_0^\infty dr \ e^{2\phi_0} \sqrt{\frac{F_1 \widetilde{F}_2 F_3}{\widetilde{F}_2 - F_3}} \ln \left| \frac{\sqrt{\widetilde{F}_2} + \sqrt{\widetilde{F}_2 - F_3}}{\sqrt{\widetilde{F}_2} - \sqrt{\widetilde{F}_2 - F_3}} \right|$$
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They are equal if and only if $H_2 = 1$, where $H_2 \equiv H_2(\tilde{F}_1, F_2, F_3, F_4)$ is another warp factor.

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$$b_{0k}(\theta) = 2R_3 \sec \theta \int_0^\infty dr \ e^{2\phi_0} \left(\frac{F_3}{H_2}\right)^{1/3} \sqrt{F_1 \tilde{F}_2} \Theta_{12}$$

$$c_{3k}(\theta) = 2R_3 \sec \theta \int_0^\infty dr \ \frac{e^{2\phi_0}}{H_2} \left(\frac{F_3}{H_2}\right)^{1/3} \sqrt{\tilde{F}_2 F_1} \Theta_{12}$$

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One can easily check that they are identical if and only of $H_2 = 1$. In fact one may check all the minimizing equations and find similar conclusion! Thus these equations are exactly solved with $H_2 = 1$!

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$$\mathcal{F}_{ab} + \epsilon_{abcd} D_c \varphi_d + 2[\varphi_a, \varphi_b] = 0$$

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Which are exactly the BHN equations! This way we recover many of the results of Kapustin and Witten using simple Hamiltonian formalism.

However the challenge is to get the boundary topological theory after twisting. Can we get this right?

This time the miracle happens from the electric and the magnetic charges Q_E and Q_M respectively.

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$$S_{bnd} = k \int_{\mathbf{W}} \operatorname{Tr} \left(\mathcal{A} \wedge d\mathcal{A} + \frac{2i}{3} \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \right) \\ + \int_{\mathbf{W}} \operatorname{Tr} \left\{ 2d_{1}\mathcal{F} \wedge \phi + \frac{2i}{3} \left(\frac{d_{1}^{3}}{k^{2}} \right) \phi \wedge \phi \wedge \phi + \left(\frac{d_{1}^{2}}{k} \right) \phi \wedge d_{\mathcal{A}} \phi \right\}$$

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$$= k \int_{\mathbf{W}} \operatorname{Tr} \left\{ \left[\mathcal{A} + \left(\frac{d_{1}}{k} \right) \phi \right] \wedge d \left[\mathcal{A} + \left(\frac{d_{1}}{k} \right) \phi \right] \right. \\ \left. + \frac{2i}{3} \left[\mathcal{A} + \left(\frac{d_{1}}{k} \right) \phi \right] \wedge \left[\mathcal{A} + \left(\frac{d_{1}}{k} \right) \phi \right] \wedge \left[\mathcal{A} + \left(\frac{d_{1}}{k} \right) \phi \right] \right\},$$

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where k and d_1 are determined from the warp-factors F_i appearing in our M-theory set-up discussed earlier.



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Conclusion and discussion

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It all started way back in 1989 with the intriguing work of Witten on connecting the Jones polynomials with Chern-Simons theory

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which has lead us to make further connections to the geometric Langland programme, Khovanov-Rozanski homology, opers and conformal blocks (that we did not discuss here).

Dasquota	(McGill)
Duogupiu	(Interaction)

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Hopefully it was not so confusing or boring! Thanks for listening.

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